



# **The typhoon model of Tropical Region Atmospheric Model System (CMA-TRAMS): development and evaluation**

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# Outline

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**1**

**Overview of TRAMS model**

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**Technical development**

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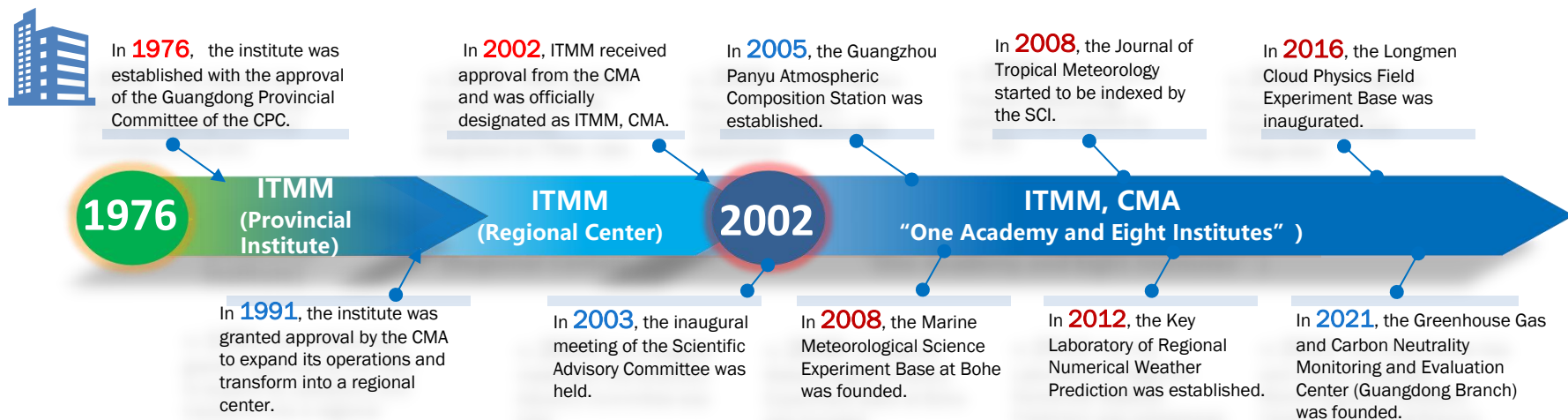
**Operational performance**

**4**

**Future plan**



- Since its establishment in 1976, the Guangzhou **Institute of Tropical and Marine Meteorology (ITMM)** has undergone 47 years of remarkable development.
- **Science directions: experimental observation** and the underlying **mechanisms** of tropical meteorology, regional **numerical modeling**, and tropical **environmental meteorology**.





Academician Qingcun Zeng, recipient of the International Meteorological Prize (IMO) and the National Top Science and Technology Award of China, serves as the director of the academic committee.



### Jointed LAB of Regional NWP



### Group photo

Key technologies in dynamic core, physical scheme, data assimilation, and ensemble forecasting have been independently developed for the regional NWP models over tropics.

Dynamic  
core

1

**3D Reference Scheme  
Predictor-Corrector Scheme**

Physical  
scheme

2

**Scale-Aware Cumulus  
Parameterization  
Tropical Convection Parameterization**

Data  
assimilation

3

**X- Band  
Phased- Array Radar Data  
MOTOR-DA**

Ensemble  
forecasting

4

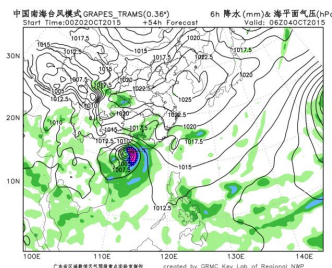
**Mesoscale EPS for TC Forecasting  
Convection-Permitting ensemble**



# Overview of TRAMS model – Historical development



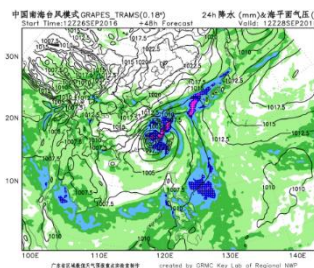
- ◆ CMA-TRAMS has been upgraded to version 3.0 with the horizontal resolution at 9 km since 2017;
- ◆ The 9-3-1 NWP system has been established since 2017 with the first 1km operation model in China.



36km

00,12UTC  
5days

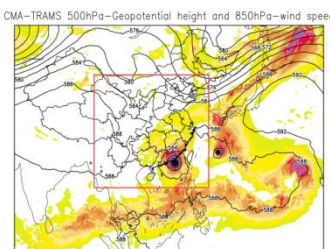
2009



18km

00,12UTC  
7days

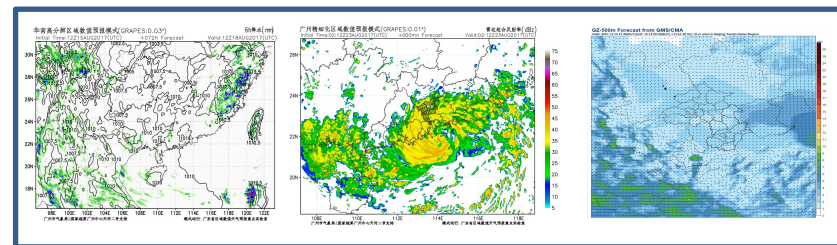
2016



9km

00,12UTC  
7days  
06,18UTC 3days

2017



3km

hourly  
24hours

2018

1km

12 minutes  
6 hours

2020

500m

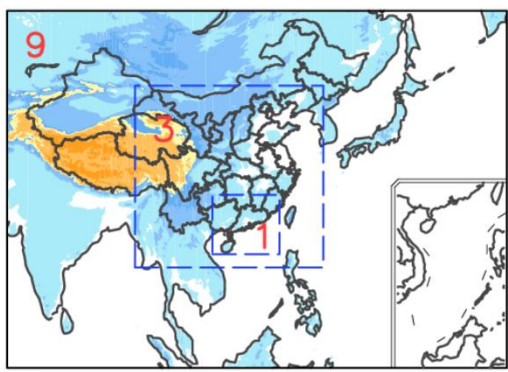
2022 Beijing  
Winter Olympic  
Games

2022

# Overview of TRAMS model



- ◆ CMA-TRAMS (9km) mainly focuses on typhoon forecasting over the Western Pacific Region; TRAMS 3km and 1km are designed for the rainfall and short-range forecast.



The domain of the CMA-TRAMS model

- ◆ The model is running based on the High Performance computer system:  
The National Supercomputer Center in Guangzhou Tianhe-2;



Guangzhou TIANHE-2

- ◆ The model is developed by the key Laboratory of Regional Numerical Weather Prediction which is jointly established by CMA and Guangdong Province;



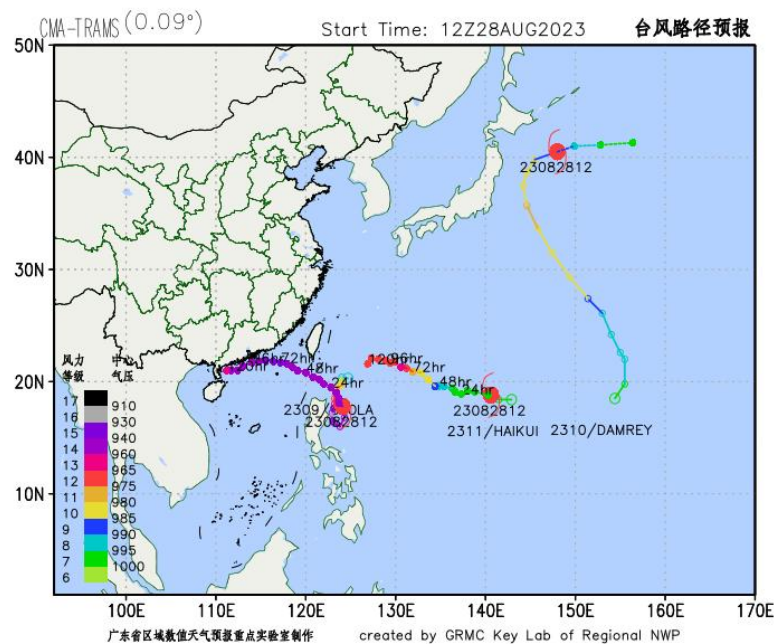
The platform of the Lab

# Overview of TRAMS model – TRAMS-9km



◆ **TRAMS-9km** is a **typhoon model**, which provides 7 days forecasting of typhoon path, typhoon intensity, as well as large-scale environmental prediction (precipitation, wind and temperature).

- ~ 9.0 km resolution
- cloud Nudging + Land-surface analysis
- 65 levels, top at 31 km
- $X*Y=1001*601$ ,  $\Delta t = 90$  s
- 4 forecasts/1D
  - LST: 08, 20 → T+168h
  - LST: 14, 02 → T+72h
- Convection: scale-aware NSAS
- MicroPhys : WSM6
- PBL: NMRF
- GWDO: KA95



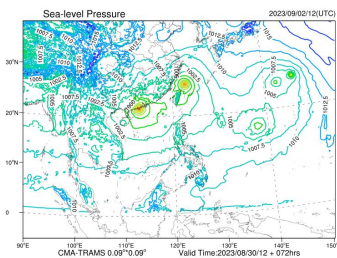
typhoon path forecasting by TRAMS-9km



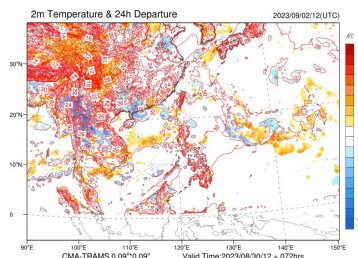
# Overview of TRAMS model – TRAMS-9km



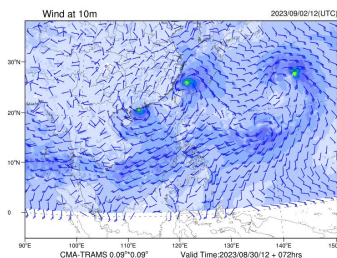
◆ The menu of **TRAMS-9km** products can be customized for the weather forecasters, e.g., the typhoon path, typhoon intensity, geo-potential height, precipitation, wind and temperature.



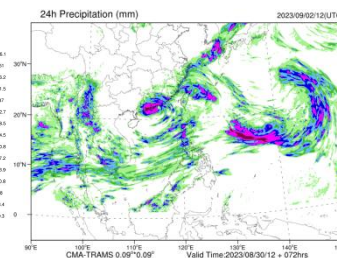
Sea-level pressure



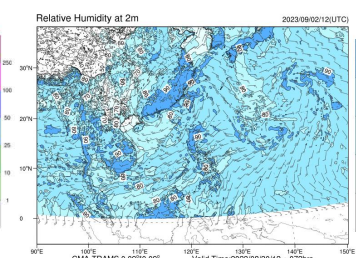
2m Temperature & 24h departure



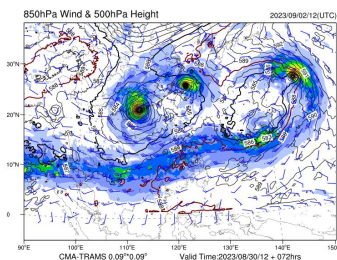
10m Wind



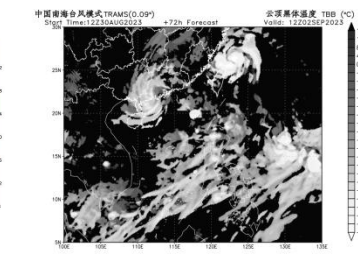
24h precipitation



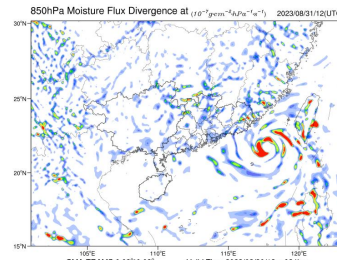
Relative humidity



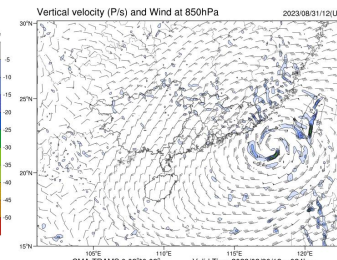
850hPa wind



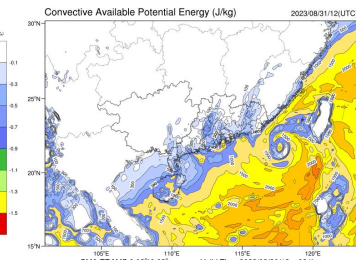
TBB (cloud-top blackbody temperature)



850 moisture flux divergence



Vertical velocity



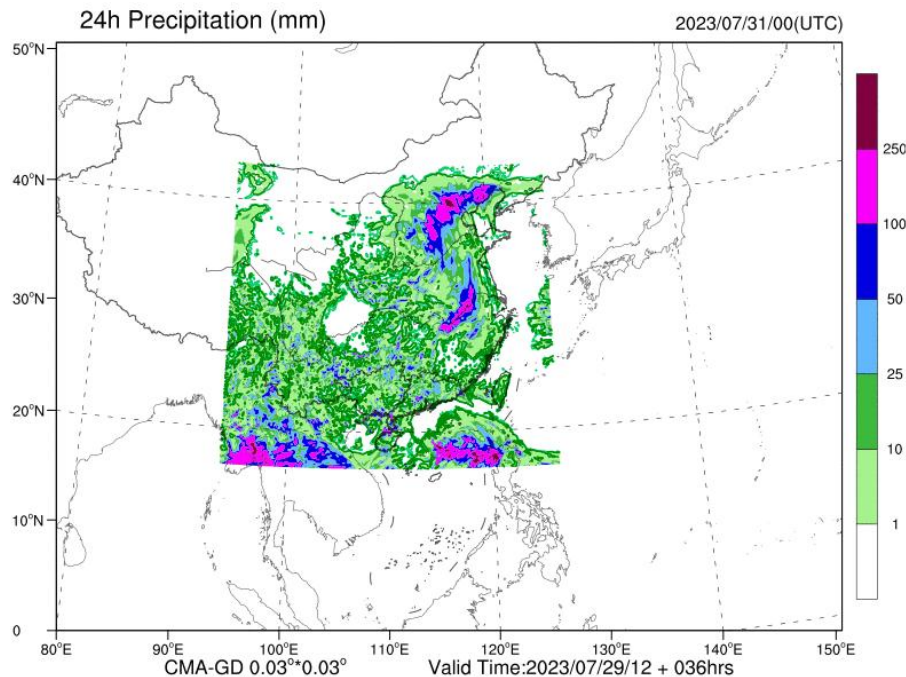
Convective available potential energy

# Overview of TRAMS model – TRAMS-3km



◆ **TRAMS-3km** is a **regional model**, which provides 4 days forecasting of regular weather elements, especially for precipitation, wind and temperature forecasting.

- ~ 3.0 km resolution
- cloud Nudging + Land-surface analysis
- 65 levels, top at 31 km
- $X*Y=1131*917$
- 2 forecasts/1D
  - 00z, 12z → T+96h
- $\Delta t = 50$  s
- Convection: scale-aware NSAS
- MicroPhys : WSM6

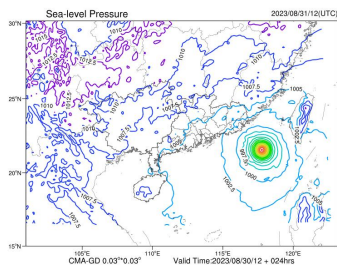


24h accumulative rainfall forecasting by TRAMS-3km

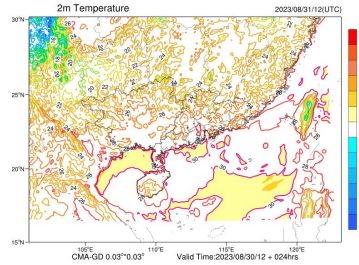
# Overview of TRAMS model – TRAMS-3km



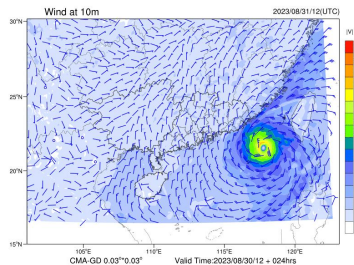
◆ The menu of TRAMS-3km products can be customized for the weather forecasters, e.g., Radar Reflectivity, geo-potential height, precipitation, wind and temperature.



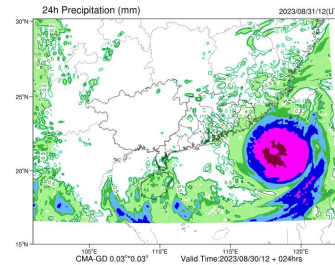
Sea-level pressure



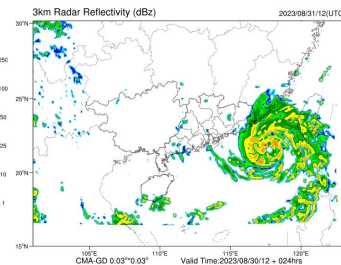
2m Temperature & 24h departure



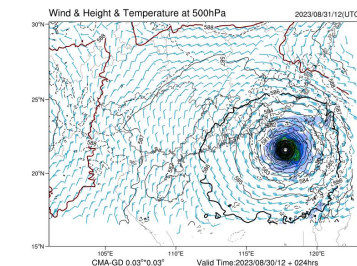
10m Wind



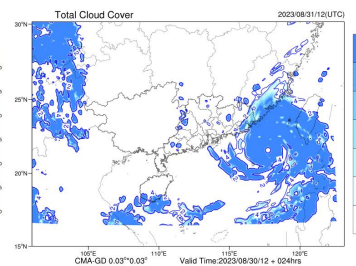
24h precipitation



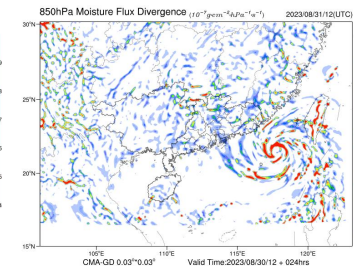
Radar Reflectivity



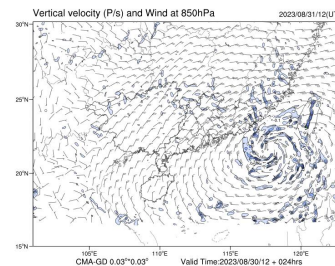
500hPa wind & height



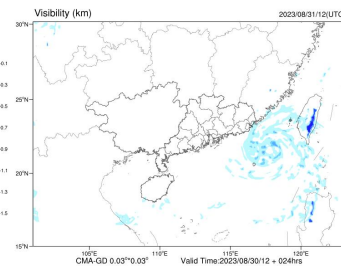
Total cloud cover



850 moisture flux divergence



Vertical velocity



Visibility

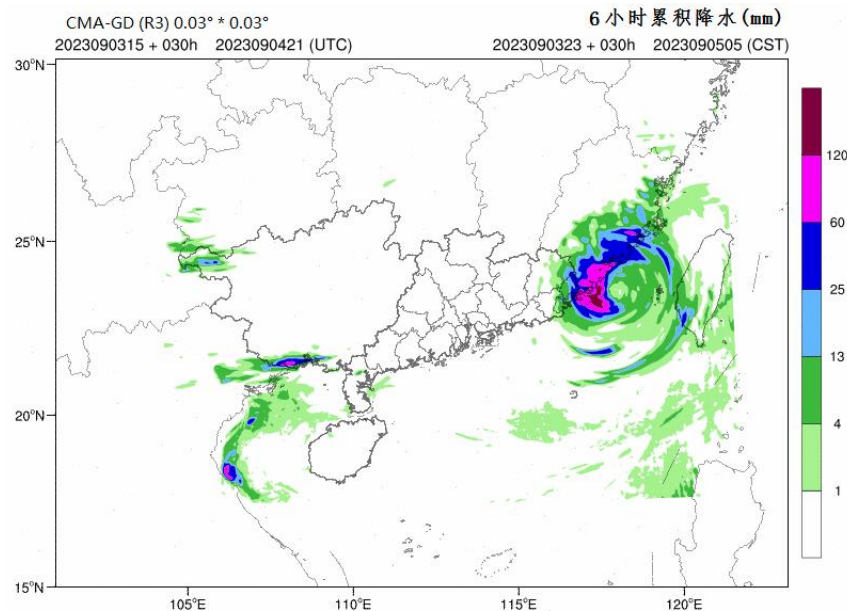


# Overview of TRAMS model – RUC-3km



◆ RUC-3km is a **hourly rapid update cycling model**, which initializes provides 30 hours for **short-range weather forecasting**.

- ~ 3.0 km resolution
- cloud Nudging +Land-surface analysis
- 65 levels, top at 31 km
- Domain coverage: 96-123.39° E;16-31.39° N
- hourly forecasts/T+30h
- $\Delta t = 50$  s
- Convection: scale-aware NSAS
- MicroPhys : WSM6



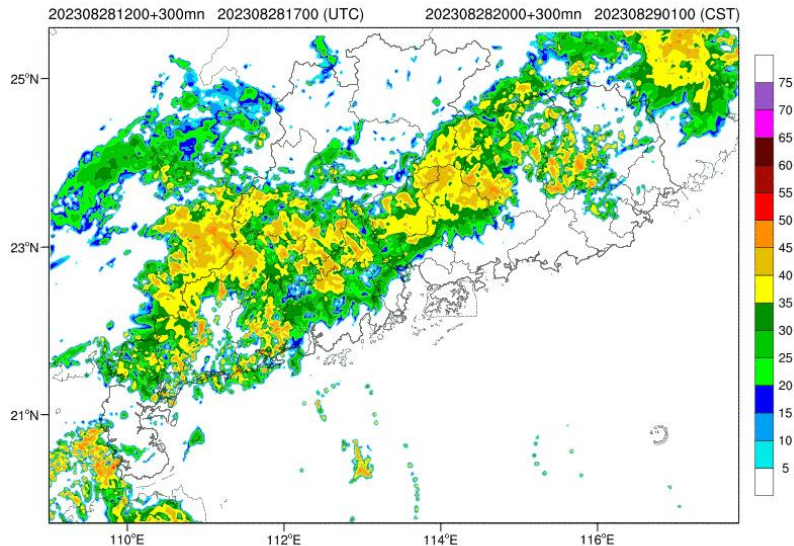
6h accumulative rainfall forecasting by TRAMS-3km

# Overview of TRAMS model – TRAMS-1km



◆ **TRAMS-1km** is a **rapid update cycling model**, which initializes for every 12 minutes and provides 6 hours for **short-range weather forecasting**.

- ~ 1.0 km resolution
- Radar data nudging
- 65 levels, top at 31 km
- $X*Y=1201*901$
- 5 forecasts/1h
  - 00min, 12min,... → T+6h
- $\Delta t = 30$  s
- Convection :not used



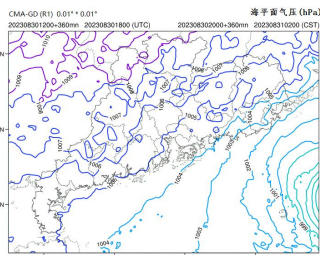
Radar reflectivity forecasting by TRAMS-1km



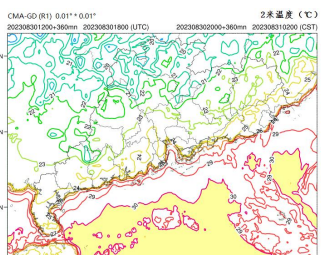
# Overview of TRAMS model – TRAMS-1km



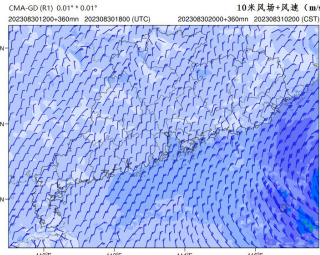
◆ The menu of TRAMS-1km products can be customized for the weather forecasters, e.g., hourly precipitation, radar reflectivity, wind and temperature.



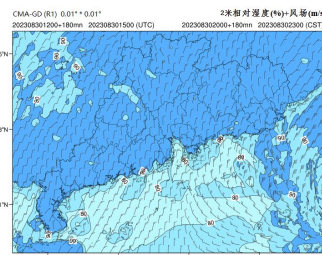
Sea-level pressure



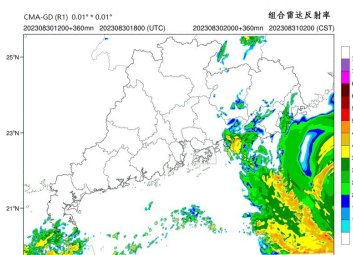
2m Temperature & 24h departure



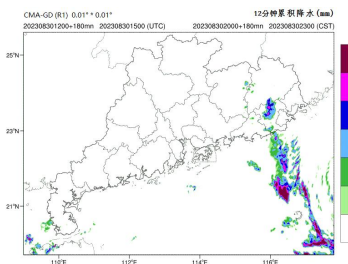
10m Wind



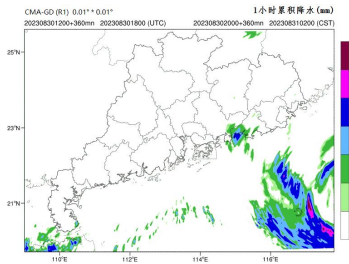
Relative humidity



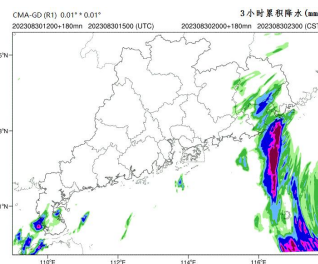
Radar Reflectivity



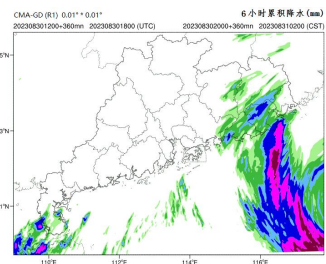
12min precipitation



1h precipitation



3h precipitation

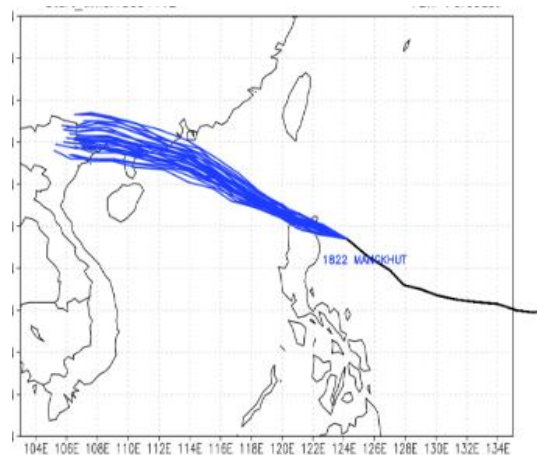


6h precipitation

# Overview of TRAMS model – Ensemble forecasting

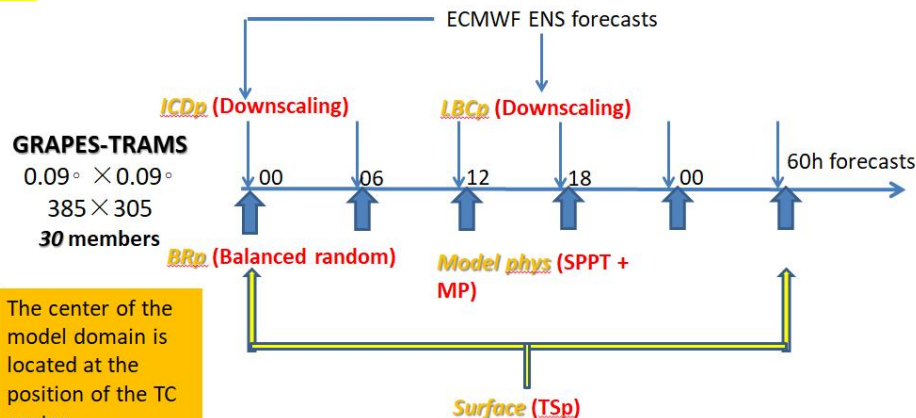


- ◆ A regional ensemble forecasting system based on TRAMS(CMA-TRAMS EPS) was running in operation with 30 members.
- ◆ Developed different perturbation techniques by considering scale characteristics and nonlinear interactions.
- ◆ Develop the "combination of multi-source and multi type disturbances" ensemble disturbance technology based on the understanding of disturbance multi-scale interactions.



**TREPS forecast of Super Typhoon Mangkhut in 2018**

## TREPS



**Design of TREPS**



# Outline

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Overview of TRAMS model

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Technical development

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Future plan

# Technical development – model upgrade



- ◆ TRAMS has been upgraded to version 3 since 2019, which including the model dynamics, model physics, data assimilation.

TRAMS-V1.0:	TRAMS-V2.0:	TRAMS-V3.0 :
1) Typhoon model(36km) 2) Regional model (9km )	1) Typhoon model (18km) 2) Regional model (3km )	1) Typhoon model: <b>9km</b> 2) Regional model : <b>3km</b> 3) Regional model : <b>1km</b>
<ul style="list-style-type: none"> <li>• Dynamics : Fully Compressible-Nonhydrostatic , Semi-Implicit Semi-Lagrangian(SISL) difference scheme,</li> <li>• 1-D Isothermal Hydrostatic Reference Atmosphere, Charney-Philip grid, (Horizontal) Isometric Lat-Lon Coordinate &amp; Arakawa-C grid,</li> <li>• implicit weighting factor=0.70.</li> </ul>	<ul style="list-style-type: none"> <li>• Dynamics upgrading:</li> <li>• SISL → <b>Iterative SISL difference scheme;</b></li> <li>• 1-D Isothermal Hydrostatic Reference Atmosphere → <b>3-D Hydrostatic Reference Atmosphere</b></li> <li>• implicit weighting factor 0.70→<b>0.55.</b></li> </ul>	<ul style="list-style-type: none"> <li>• Dynamics upgrading:</li> <li>• →new <b>Iterative SISL difference scheme;</b></li> <li>• →new <b>3-D Hydrostatic Reference Atmosphere</b></li> <li>• Adding new assistive scheme like</li> <li>• <b>4<sup>th</sup> order horizontal diffusion and weak w_damping,</b></li> </ul>
<ul style="list-style-type: none"> <li>• Physics: Microphysics(WSM6),</li> <li>• Long-Wave&amp;Short-Wave Radiation(RRTM), Surface Layer(M-O similarity theory),</li> <li>• Boundary layer(MRF),</li> <li>• Land Surface(SLAB), Cumulus</li> <li>• Convection(SAS).</li> </ul>	<ul style="list-style-type: none"> <li>• Physics upgrading:</li> <li>• Boundary layer(MRF→<b>NMRF</b>),</li> <li>• Land Surface(SLAB→<b>SMS</b>),</li> <li>• Cumulus Convection(TY:SAS→<b>NSAS</b>; MESO:SAS).</li> </ul>	<ul style="list-style-type: none"> <li>• Physics upgrading: Microphysics(WSM6→<b>New WSM6</b>),</li> <li>• Long-Wave&amp;Short Wave Radiation(RRTM→<b>RRTMG</b>),</li> <li>• Surface Layer(<b>improved SFCLAY</b>),</li> <li>• Land Surface(SMS,<b>LAND SF ANALYSIS</b>),</li> <li>• Cumulus Convection(<b>scaleaware SAS</b>).</li> </ul>

Upgrade of TRAMS model



- Three-dimensional (3D) 3D static atmospheric reference
- Step by step calculation of nonlinear terms
- Lagrangian advection correction
- Coupling Scheme of Physical and Dynamic Processes
- High order precision central difference scheme with non-uniform grids
- A New Algorithm for 3D Lagrangian Vector Projection
- A second-order precision vertical difference scheme under non-uniform layering
- Heating term of continuous equation and influence of water substance

# Technical development – 3D static atmospheric reference

- ◆ The 3D static atmospheric reference method greatly reduces non-static equilibrium disturbances, which is beneficial for reducing model prediction errors, especially in complex terrain areas.
- ◆ The scheme has been adopted into CMA-GFS V3.0 for the new model dynamics.

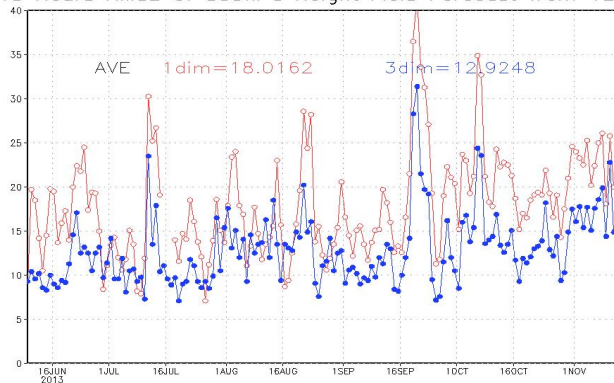
$$\Pi(\lambda, \varphi, z, t) = \bar{\Pi}(\lambda, \varphi, z) + \Pi'(\lambda, \varphi, z, t) \quad (2-1-8)$$

$$\theta(\lambda, \varphi, z, t) = \bar{\theta}(\lambda, \varphi, z) + \theta'(\lambda, \varphi, z, t) \quad (2-1-9) \quad \psi$$

$$T(\lambda, \varphi, z, t) = \bar{T}(\lambda, \varphi, z) + T'(\lambda, \varphi, z, t) \quad (2-1-10)$$

Divide the model atmosphere into two parts that satisfy static equilibrium and its deviation

48 Hours RMSE of 850hPa Height Field Forecast from 12:00



$$\frac{du}{dt} = -\frac{C_p \theta}{a \cos \varphi} \frac{\partial \Pi'}{\partial \lambda} - \frac{C_p \theta}{a \cos \varphi} \frac{\partial \bar{\Pi}}{\partial \lambda} + f_v + F_u + \delta_M G_u - \delta_\varphi f_\varphi w \dots$$

$$\frac{dv}{dt} = -\frac{C_p \theta}{a} \frac{\partial \Pi'}{\partial \varphi} - \frac{C_p \theta}{a} \frac{\partial \bar{\Pi}}{\partial \varphi} - f_u + F_v - \delta_M G_v \dots$$

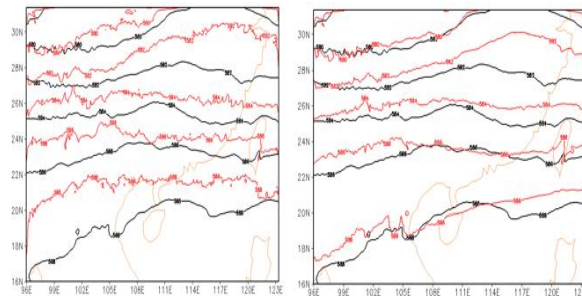
$$\delta_{NH} \frac{dw}{dt} = -C_p \theta \frac{\partial \Pi'}{\partial z} - C_p \theta \frac{\partial \bar{\Pi}}{\partial z} + F_w + \delta_M G_w + \delta_\varphi f_\varphi u \dots$$

$$\frac{d\Pi'}{dt} = -\frac{d\bar{\Pi}}{dt} - \frac{\Pi'}{(\gamma-1)} \frac{D_3}{D_3} + \frac{F_\theta^*}{(\gamma-1)\theta} \quad (2-1-14) \quad \psi$$

$$\frac{d\theta'}{dt} = -\frac{d\bar{\theta}}{dt} + \frac{F_\theta^*}{\bar{\Pi}} \quad (2-1-15) \quad \psi$$

1D

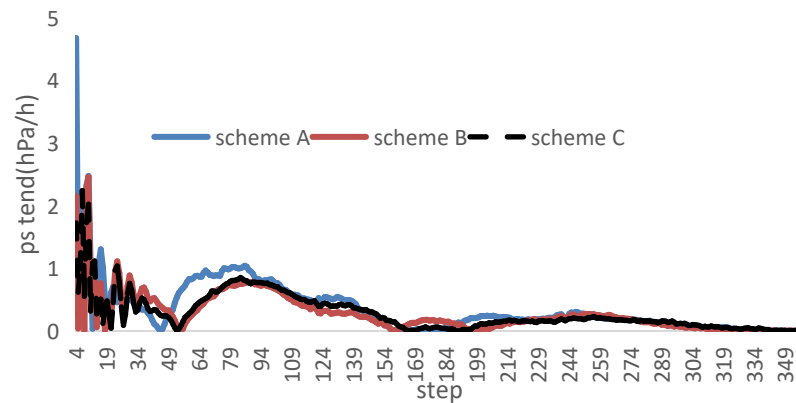
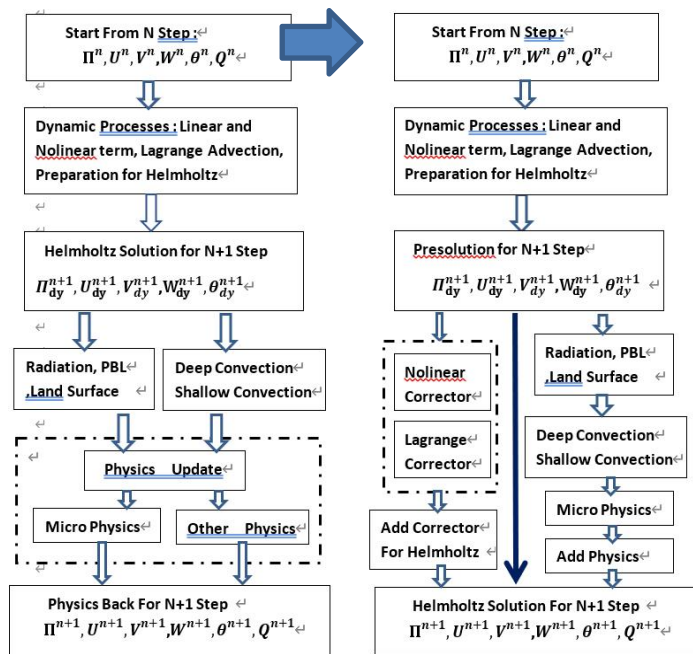
3D



Comparison of 24-hour forecast for geopotential height(500hPa)  
(red line: forecast; black line: analysis of the field)

# Technical development –coupling between dynamic and Physics

- ◆ By Using the estimation correction method and considering the effect of hydrothermal physical feedback on the continuous equation, **the physical feedback of n+1 time step is used as a prediction increment to participate in solving the Helmholtz equation**, forming a coupling between physical and dynamic processes, and improving the overall prediction performance of the model



The initial integrated pressure increment of the model is smaller in the disturbance amplitude of the new scheme B compared to the original scheme A, which is beneficial for improving the accuracy of model.



# Technical development –high-order precision differential schemes

- ◆ The ideal experiments were conducted for vertical direction with a 2nd order and a horizontal 4th order differential schemes to improve the accuracy of the model.

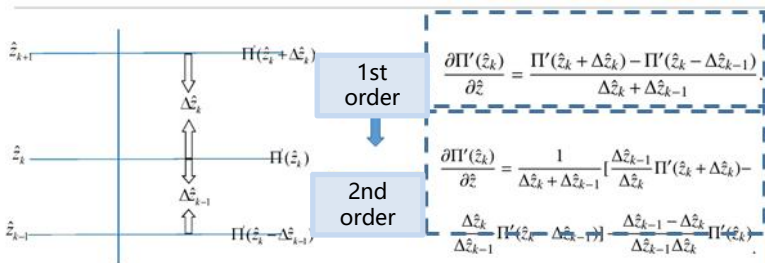
Second order

fourth order

sixth order

Table 1 Difference Schemes with 2<sup>nd</sup>, 4<sup>th</sup> and 6<sup>th</sup> order accuracy<sup>41</sup>

First derivative	Second derivative
$\frac{f_{i+1} - f_{i-1}}{2\Delta x}$	$\frac{f_{i-1} - 2f_i + f_{i+1}}{\Delta x^2}$
$\frac{f_{i-2} - 8f_{i-1} + 8f_{i+1} - f_{i+2}}{12\Delta x}$	$\frac{-f_{i-2} + 16f_{i-1} - 30f_i + 16f_{i+1} - f_{i+2}}{12\Delta x^2}$
$\frac{-f_{i-3} + 9f_{i-2} - 45f_{i-1} + 45f_{i+1} - 9f_{i+2} + f_{i+3}}{60\Delta x}$	$\frac{-2f_{i-3} + 27f_{i-2} - 270f_{i-1} + 490f_i - 270f_{i+1} + 27f_{i+2} - 2f_{i+3}}{180\Delta x^2}$



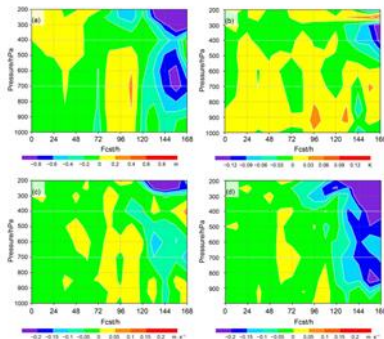
$$u^{n+1} = (\xi_{u1} \frac{1}{a \cos \varphi} \frac{\partial}{\partial \lambda} + \xi_{u2} \frac{1}{a} \frac{\partial}{\partial \varphi} + \xi_{u3} \frac{\partial}{\partial z}) \Pi' + \xi_{u0}, \quad (1)$$

$$v^{n+1} = (\xi_{v1} \frac{1}{a \cos \varphi} \frac{\partial}{\partial \lambda} + \xi_{v2} \frac{1}{a} \frac{\partial}{\partial \varphi} + \xi_{v3} \frac{\partial}{\partial z}) \Pi' + \xi_{v0}, \quad (2)$$

$$\dot{w}^{n+1} = (\xi_{w1} \frac{1}{a \cos \varphi} \frac{\partial}{\partial \lambda} + \xi_{w2} \frac{1}{a} \frac{\partial}{\partial \varphi} + \xi_{w3} \frac{\partial}{\partial z}) \Pi' + \xi_{w0}, \quad (3)$$

$$\theta^{n+1} = (\xi_{\theta1} \frac{1}{a \cos \varphi} \frac{\partial}{\partial \lambda} + \xi_{\theta2} \frac{1}{a} \frac{\partial}{\partial \varphi} + \xi_{\theta3} \frac{\partial}{\partial z}) \Pi' + \xi_{\theta0}, \quad (4)$$

$$\Pi'^{n+1} = \xi_{\Pi1} u^{n+1} + \xi_{\Pi2} v^{n+1} + \xi_{\Pi3} \dot{w}^{n+1} + \xi_{\Pi} \frac{\partial D_1}{\partial z} + A_{\Pi}, \quad (5)$$

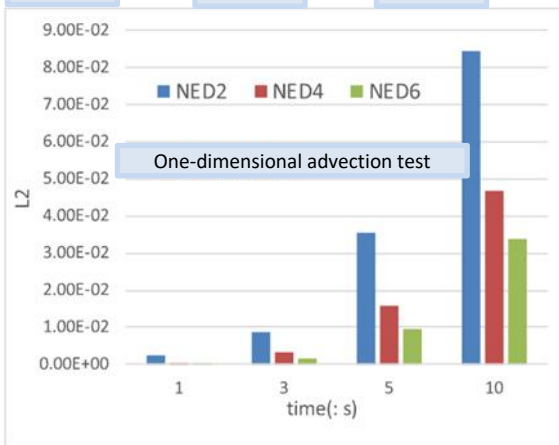


$$\frac{\Delta x_{i-3}}{i-3} \quad \frac{\Delta x_{i-2}}{i-2} \quad \frac{\Delta x_{i-1}}{i-1} \quad \frac{\Delta x_i}{i} \quad \frac{\Delta x_{i+1}}{i+1} \quad \frac{\Delta x_{i+2}}{i+2} \quad \frac{\Delta x_{i+3}}{i+3}$$

2nd order

4th order

6th order





# Technical development – Lagrangian 3D vector projection

- ◆ The Lagrangian 3D vector projection technology is developed to improve model calculation efficiency with significant reduction in computational complexity.

$$A_u = \Delta t \alpha_\varepsilon (\bar{N}_u)^n + (Y_u)^n_* \cos(\varrho - \lambda_*) + (Y_v)^n_* \sin \varphi_* \sin(\lambda - \lambda_*) \\ - (Y_w)^n_* \cos \varphi_* \sin(\lambda - \lambda_*)$$

$$A_v = \Delta t \alpha_\varepsilon (\bar{N}_v)^n + (Y_u)^n_* \sin \varphi_* \sin(\lambda - \lambda_*) + (Y_v)^n_* (\cos \varphi_* \cos \varphi_* + \sin \varphi_* \sin \varphi_* \cos(\lambda - \lambda_*)) \\ + (Y_w)^n_* (\cos \varphi_* \sin \varphi_* - \sin \varphi_* \cos \varphi_* \cos(\lambda - \lambda_*))$$

$$A_w = \Delta t \alpha_\varepsilon (\bar{N}_w)^n + (Y_u)^n_* \cos \varphi_* \sin(\lambda - \lambda_*) + (Y_v)^n_* (\sin \varphi_* \cos \varphi_* - \cos \varphi_* \sin \varphi_* \cos(\lambda - \lambda_*)) \\ + (Y_w)^n_* (\sin \varphi_* \sin \varphi_* + \cos \varphi_* \cos \varphi_* \cos(\lambda - \lambda_*))$$

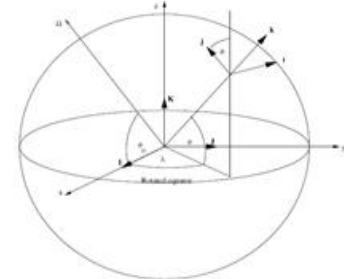
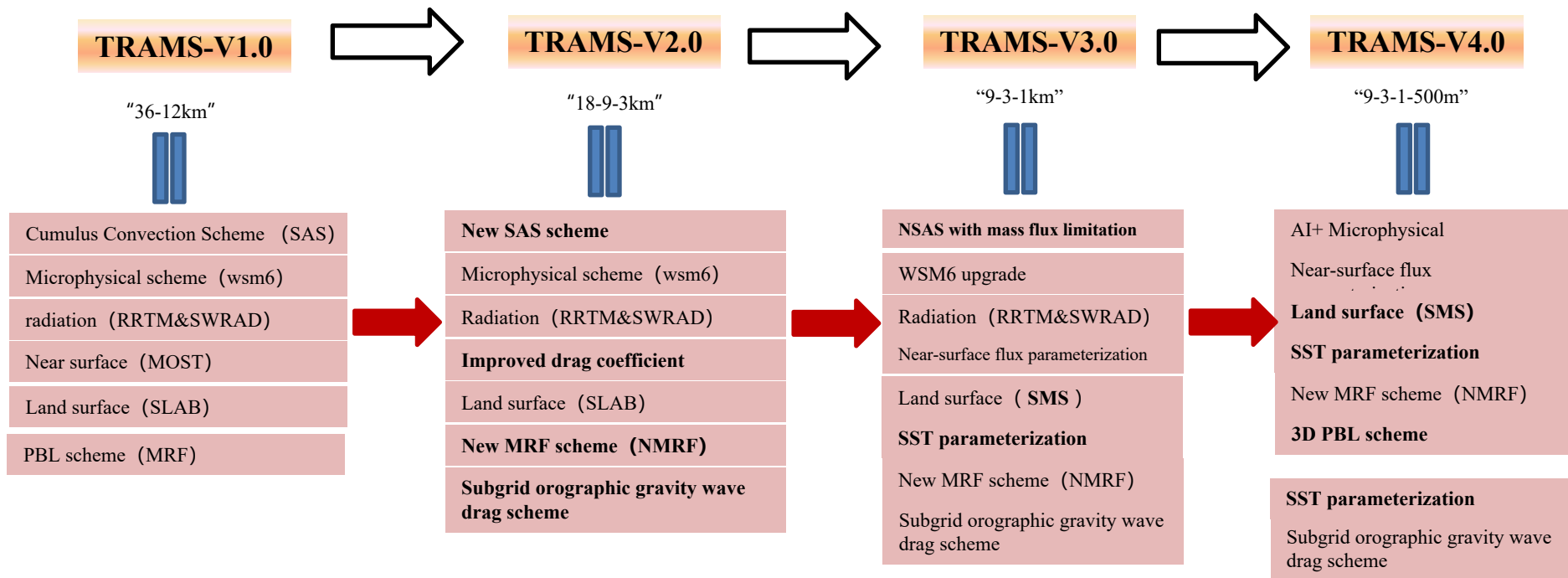


Figure 2.5: Depicting the unit vectors  $\mathbf{i}, \mathbf{j}, \mathbf{k}$  associated with the direction  $(\lambda, \varphi)$  in the rotated system, and the unit vectors  $\mathbf{i}^*, \mathbf{j}^*, \mathbf{k}^*$  associated with the standard, nonrotated system

The improvement scheme refers to the approach of UK-MET, which uniformly projects the unit vectors of all arrival and departure points onto a fixed unit vector at the center of the sphere. The improved scheme has the same accuracy as the original scheme, but the computational complexity is significantly reduced.

# Technical development – Model physics

- The TRAMS model has been upgraded and developed, forming a set of high-resolution model physics solutions suitable for the tropical region(subgrid orographic parameterization, ocean boundary layer, land surface model, etc.)



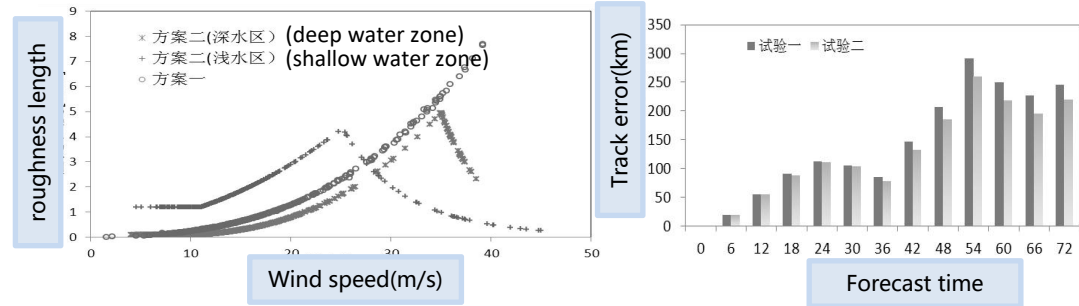
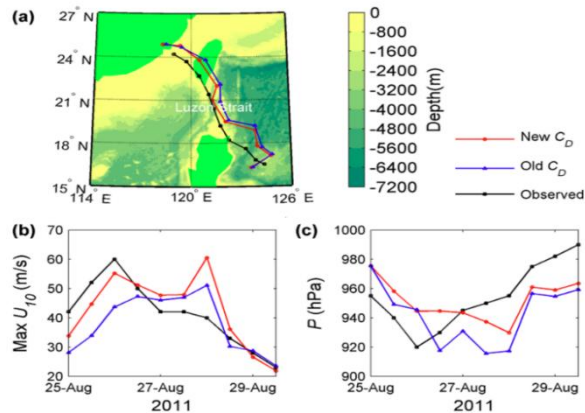
# Technical development – PBL scheme

- Based on the observation data of the Bohe Ocean Meteorological Observation Platform, the following relationship between drag coefficient ( $C_D$ ) based on the water depth ( $d$ ) and wind speed ( $U_{10}$ ) by using the method of function fitting statistics:

$$1000 \times C_D = \max \left\{ \frac{h}{b + \tanh\left(\frac{gd}{U_{c\infty}^2}\right)^b}, \frac{\exp\left[-\frac{(U_{10} - U_{ref})^2}{gd}\right]}{\tanh\left(\frac{gd}{U_{c\infty}^2}\right)^b} (p(1)\tilde{u}^2 + p(2)\tilde{u} + p(3)) \right\},$$

Convert the drag coefficient to roughness ( $z_0$ ):

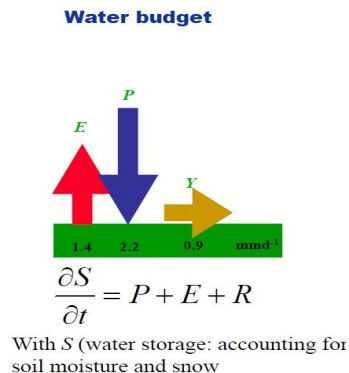
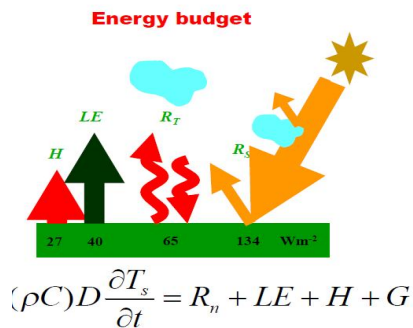
$$1000 \times z_0 = \begin{cases} 15.6 \frac{U_{10}^2}{g} + 10^{-2} & U_{10} < 35 \text{ ms}^{-1} \\ 2.82 & U_{10} \geq 35 \text{ ms}^{-1} \end{cases}$$



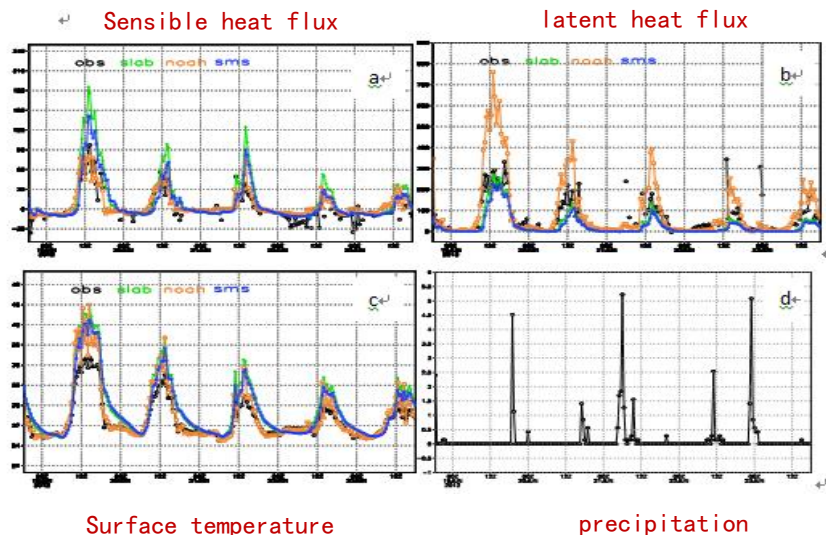
The improved  $C_D$  scheme has significantly improved the typhoon path and intensity forecast.

# Technical development – Land surface scheme

- ◆ The prediction of soil moisture plays an important role in land surface processes. The coupling of land surface and boundary layer fluxes was implemented to improve the prediction of near-surface elements.
- ◆ A simplified land surface solution has been developed, which considers the daily changes in shallow soil moisture prediction and thin layer soil bottom temperature, which can improve the high sensible heat flux and virtual high latent heat.



Using the forced recovery method to calculate the daily variation of bottom temperature of thin soil layers can simplify soil heat balance.



# Technical development – Subgrid orographic parameterization

- ◆ A subgrid orographic parameterization scheme was proposed to consider the near-surface wind field feedback, and add momentum deposition term in the momentum balance equation.

$$\mathbf{A}\mathbf{M}_v = \mathbf{F}_{sd}. \quad (1)$$

The vector of momentum tendency  $\mathbf{M}_v$  is solved using the matrix  $\mathbf{A}$  and forcing  $\mathbf{F}_{sd}$ ,

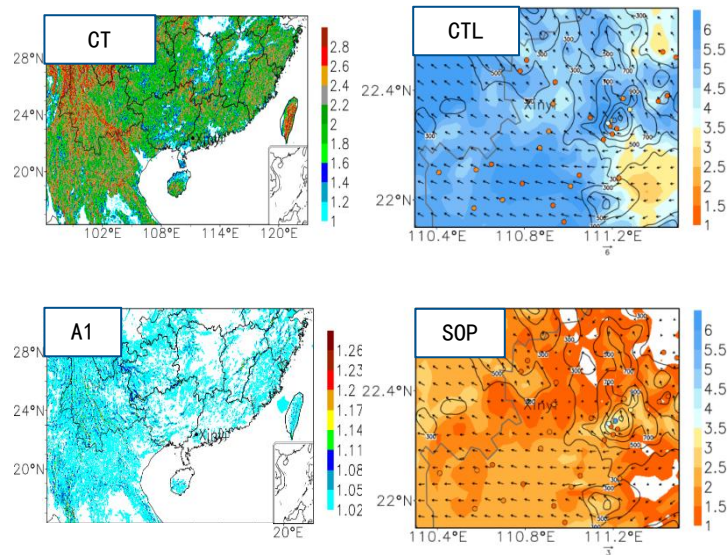
where the main diagonal of  $\mathbf{A}$  on the first model level is defined as  $A_1$ :

$$A_1 = (1 + \delta_1); \quad (2)$$

$$\delta_1 = 2c_t\rho g \frac{u_s^2}{S\Delta z} dt. \quad (3)$$

Here, the subscript “1” stands for the first model level,  $\rho$  is the air density,  $g$  is the acceleration due to gravity,  $\delta_1$  represents the sink term,  $S$  is the wind speed at the first model level,  $u_s$  is the friction velocity, and  $\Delta z$  is the thickness of the first model layer.  $c_t$  is a function of  $\Delta^2 h'_{i,j}$  and the standard deviation  $\sigma'_{sso}$ :

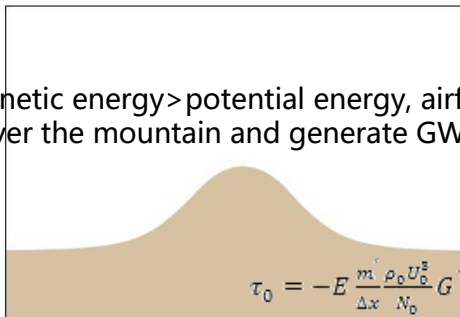
$$c_t = \begin{cases} 1, \Delta^2 h'_{i,j} > -20, \sigma'_{sso} < e \\ \ln \sigma'_{sso}, -10 < \Delta^2 h'_{i,j}, \sigma'_{sso} > e \\ \alpha \ln \sigma'_{sso} + (1 - \alpha), -10 > \Delta^2 h'_{i,j} > -20, c \\ \frac{\Delta^2 h' + 30}{10}, -20 > \Delta^2 h'_{i,j} > -30 \\ 0, \Delta^2 h'_{i,j} < -30 \end{cases}$$



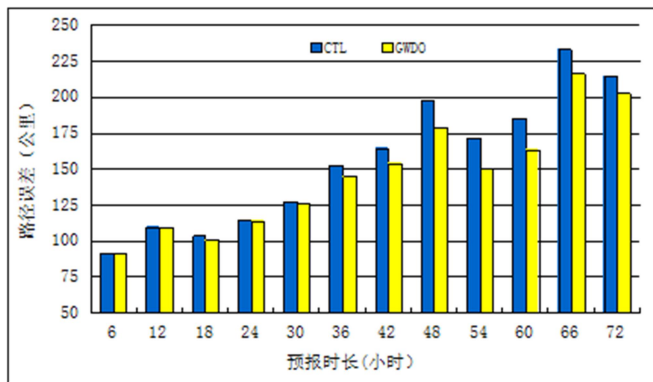
The new scheme significantly reduces the overestimation of low-level wind speed

# Technical development – orographic gravity wave drag parameterization

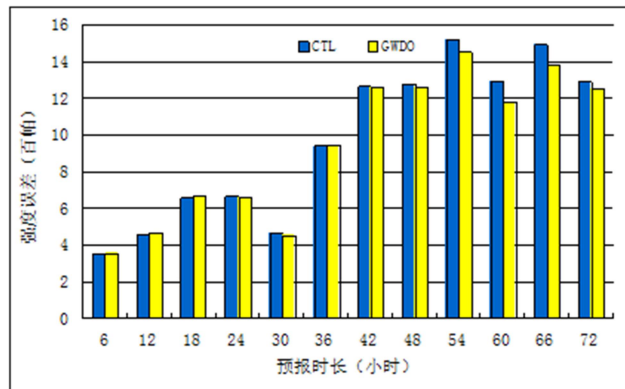
Kinetic energy > potential energy, airflow goes over the mountain and generate GWD



- The subgrid **orographic gravity wave drag parameterization** scheme has been implemented in TRAMS model.
- **GWD** parameterization has **effectively improved the overall performance of TRAMS for typhoon forecasting**.



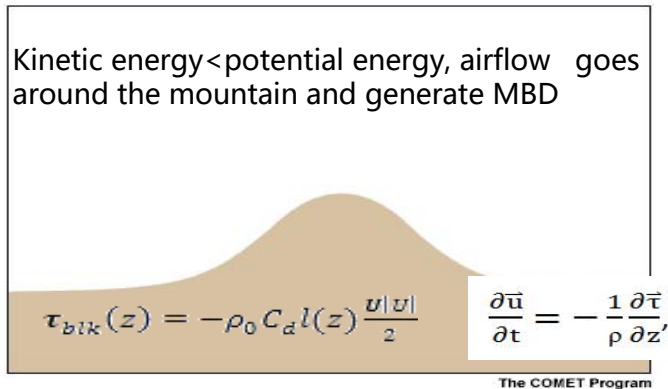
track error



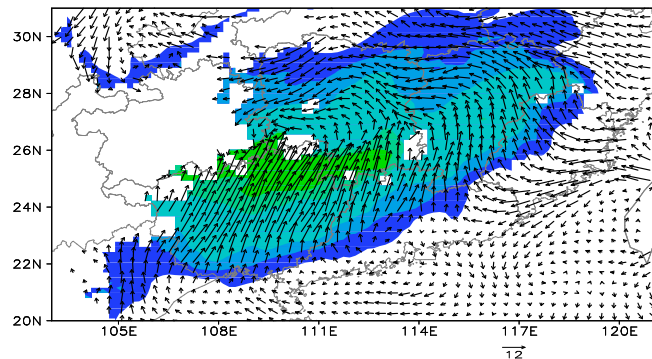
intensity error

The mean error comparison between CTL and GWDO experiment of 9 landing typhoons

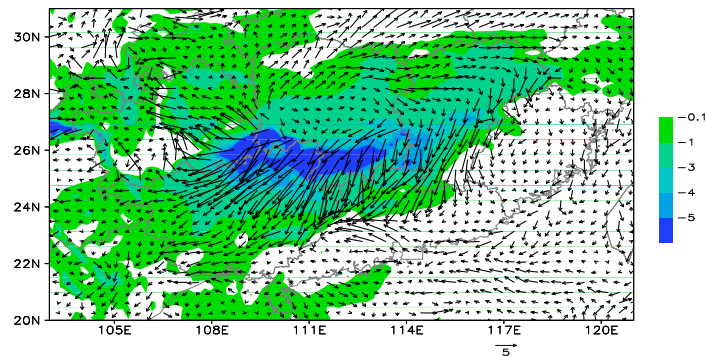
# Technical development – Mountain blocking drag parameterization



- The subgrid Mountain blocking drag **parameterization** scheme has been implemented in TRAMS model.
- MBD has effectively improved the simulation of low-level southerly winds and high surface temperatures in winter and spring, which alleviated the southerly bias and weakened the excessive temperature deviation caused by strong southerly winds in the operational forecasting.



CTL(48hr)-ANA

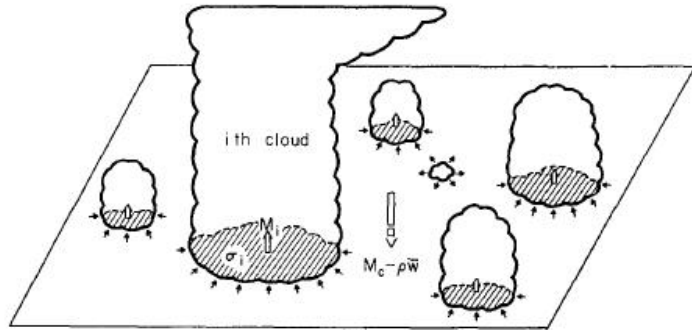


GWDO+MBD-CTL





# Technical development – scale aware SAS scheme



$$\bar{h} = \sigma h_c + (1 - \sigma) \tilde{h}$$

$$\bar{q} = \sigma q_c + (1 - \sigma) \tilde{q}$$

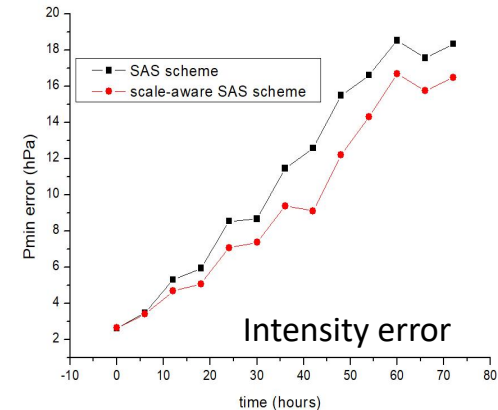
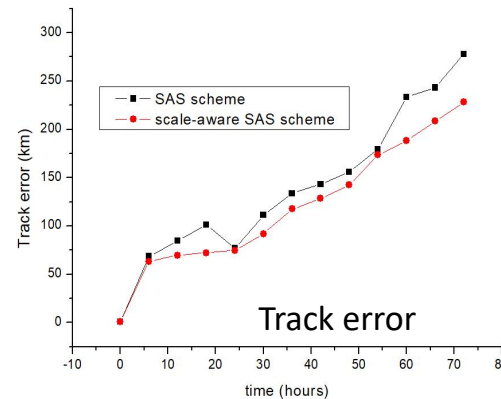
$$\bar{w} = \sigma w_c + (1 - \sigma) \tilde{w}$$

$$\sigma_u = \frac{3.14 R_c^2}{A_{grid}}, R_c = \frac{0.2}{\varepsilon_0}$$

$$\frac{\partial \bar{h}}{\partial t_{conv}} = -\frac{1}{\rho} (E \tilde{h} - D h_c) + \frac{1}{\rho} \frac{\partial}{\partial z} \left[ M_c \tilde{h} + \rho \bar{w} (\bar{h} - \tilde{h}) \right]$$

$$\frac{\partial \bar{q}}{\partial t_{conv}} = -\frac{1}{\rho} (E \tilde{q} - D q_c) + \frac{1}{\rho} \frac{\partial}{\partial z} \left[ M_c \tilde{q} + \rho \bar{w} (\bar{q} - \tilde{q}) \right]$$

- The impacts of the convection by considering the coverage rate of the cloud (scale-aware) was included.
- The scale aware SAS scheme was implemented into TRAMS model, which improves the typhoon forecasting of track and intensity, as well as the heavy rainfall forecasting.





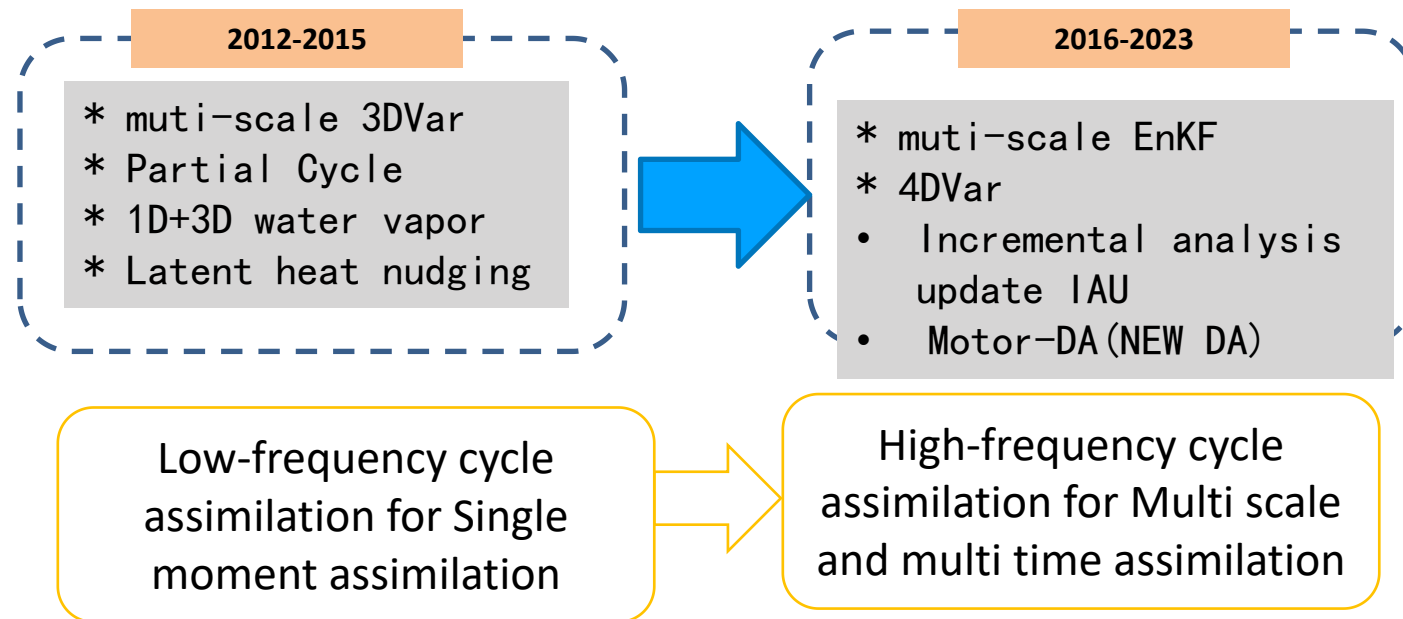


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- ◆ New Generation Data Assimilation
- ◆ Technology of Multi-scale 3DVAR
- ◆ Application Technology of Satellite Data Assimilation
- ◆ Cloud Analysis (ADAS System) and warm Start Technology
- ◆ Radar water vapor (1D+3DVAR)
- ◆ Surface precipitation latent heat nudging

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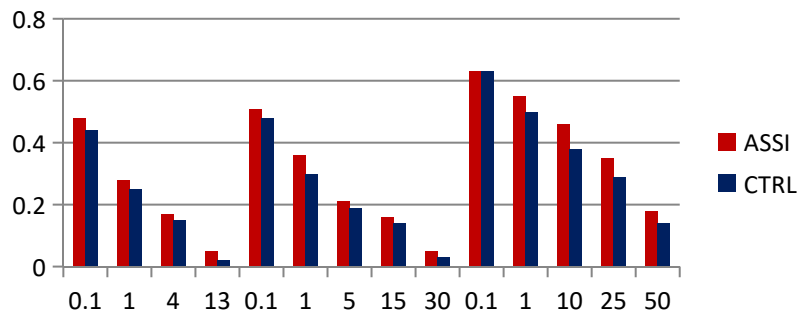
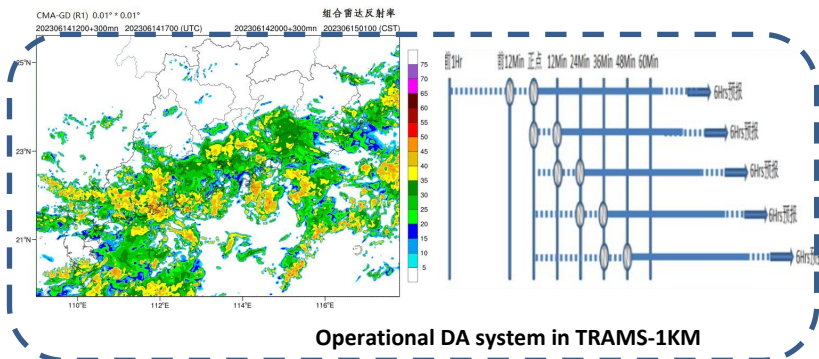
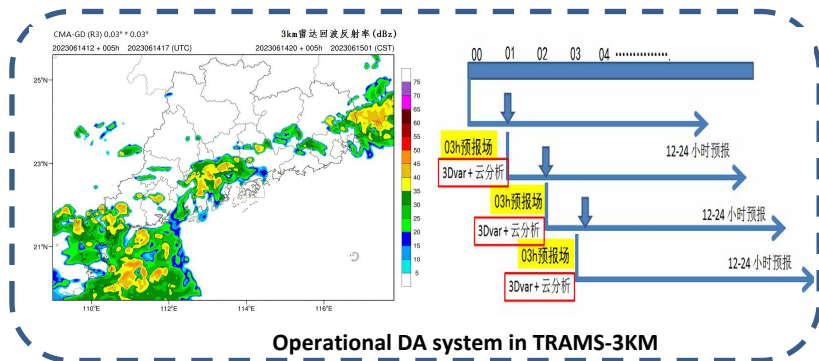
# Technical development – Data assimilation



	data type	observed frequency
Satellite	EUMETSAT	Real time
	Himawari-8	10min
	FY2	15min
	FY3	15min
	FY4	15-18min
radar	GNSS/MET	hourly
	radar	6min
	Wind profile radar	5-10min
	X-band phased array radar	90sec
satiation	sounding	00UTC/12UTC
	Surface observation	hourly
	automatic station	6min
	buoy station	6min
	Island Station	6min
	Platform	6min
else	Aircraft	hourly
	Lightning positioning station	6min

# Technical development – Operational DA system

- ◆ The cloud analysis system has been in operation in the TRAMS-3KM and TRAMS 1KM model.
- ◆ The radar reflectivity data and FY-2G TBB data was used in the cloud analysis system.
- ◆ It can improve the operational forecasting ability of the rapidly update cycling system.



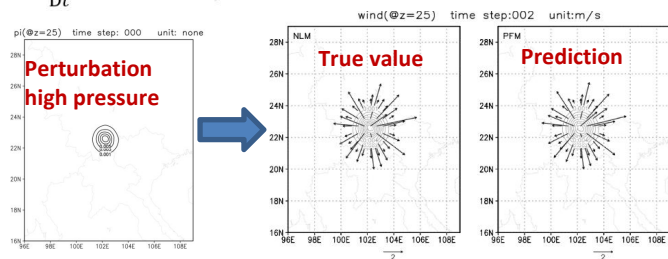
6h, 12h, 24h forecast average precipitation TS of different scales  
Blue: Before assimilation; Red: After assimilation



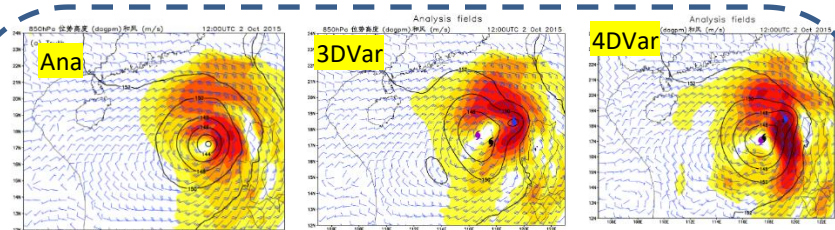
# Technical development – 4Dvar assimilation

- ◆ Strictly derive perturbation equations from the original GRAPES equations and establish a perturbation prediction model.
- ◆ Developed a 4D-Var system framework based on disturbance patterns and built a new generation of assimilation system

$$\begin{aligned}\frac{Du'}{Dt} &= -(u'u_x + v'u_y + \hat{w}'u_z) + C_P L_{\pi x} \theta' + L_\theta (\Pi'_x + Z_{sx} \Pi'_z) + f v' \epsilon \\ \frac{Dv'}{Dt} &= -(u'v_x + v'v_y + \hat{w}'v_z) + C_P L_{\pi y} \theta' + L_\theta (\Pi'_y + Z_{sy} \Pi'_z) - f u' \epsilon \\ \frac{Dw'}{Dt} &= -(u'w_x + v'w_y + \hat{w}'w_z) + C_P L_{\pi z} \theta' + L_\theta Z_{sz} \Pi'_z \epsilon \\ \frac{D\Pi'}{Dt} &= -(u'\Pi_x + v'\Pi_y + \hat{w}'\Pi_z) - \alpha_D \Pi' - \alpha_\Pi D'_3 + \gamma_\theta P'_w \epsilon \\ \frac{D\theta'}{Dt} &= -(u'\theta_x + v'\theta_y + \hat{w}'\theta_z) + \gamma_\Pi P'_w \epsilon \\ \frac{Dq'}{Dt} &= -(u'q_x + v'q_y + \hat{w}'q_z) - P'_w \epsilon\end{aligned}$$



Rapid propagation of inertial gravity waves



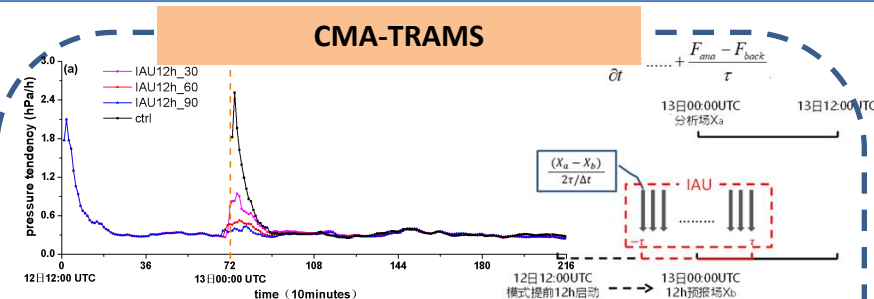
850hPa Wind and Potential Height

预报时效 <sup>←</sup>	位置偏差 (km) <sup>←</sup>				
	3DVar_1 <sup>←</sup>	3DVar_2 <sup>←</sup>	4DVar_1 <sup>←</sup>	4DVar_2 <sup>←</sup>	CTL <sup>←</sup>
00h <sup>←</sup>	115.1 <sup>←</sup>	73.9 <sup>←</sup>	30.8 <sup>←</sup>	54.0 <sup>←</sup>	230.8 <sup>←</sup>
06h <sup>←</sup>	92.5 <sup>←</sup>	95.4 <sup>←</sup>	21.1 <sup>←</sup>	21.1 <sup>←</sup>	218.1 <sup>←</sup>
12h <sup>←</sup>	74.5 <sup>←</sup>	39.4 <sup>←</sup>	24.7 <sup>←</sup>	11.2 <sup>←</sup>	196.1 <sup>←</sup>
18h <sup>←</sup>	73.4 <sup>←</sup>	15.3 <sup>←</sup>	33.4 <sup>←</sup>	33.4 <sup>←</sup>	168.1 <sup>←</sup>
24h <sup>←</sup>	84.3 <sup>←</sup>	53.2 <sup>←</sup>	35.0 <sup>←</sup>	30.5 <sup>←</sup>	142.4 <sup>←</sup>
30h <sup>←</sup>	103.6 <sup>←</sup>	56.3 <sup>←</sup>	15.2 <sup>←</sup>	10.4 <sup>←</sup>	99.9 <sup>←</sup>
36h <sup>←</sup>	83.4 <sup>←</sup>	45.4 <sup>←</sup>	15.2 <sup>←</sup>	20.7 <sup>←</sup>	75.7 <sup>←</sup>

track error of typhoon " Mujigae " by different assimilation schemes

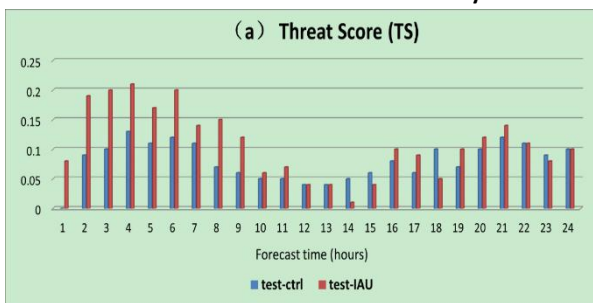
# Technical development – IAU initialization method

- ◆ Develop **incremental analysis update (IAU) initialization** technology to gradually add assimilation analysis increments to the model, which could **alleviate the initial noise**, and achieve faster coordination of the model forecast.
- ◆ **IAU technology** has been used in **CMA-GFS**.

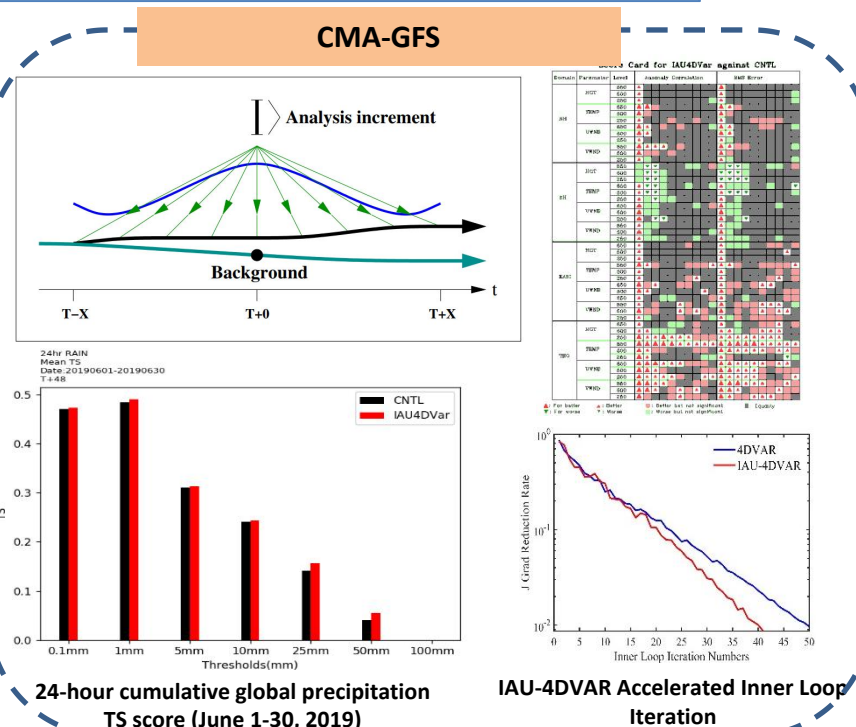


different relaxation durations on the tendency

(a) Threat Score (TS)

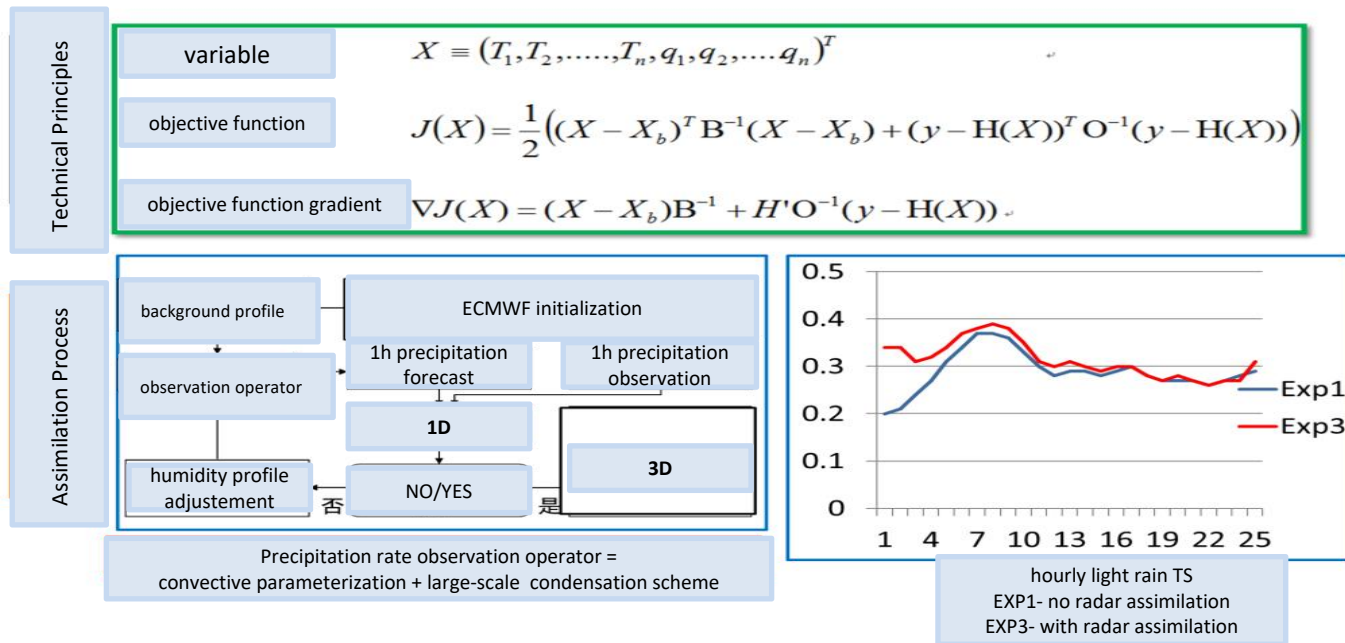


Hourly Precipitation Forecast TS Score -  
(April 1-30, 2019)

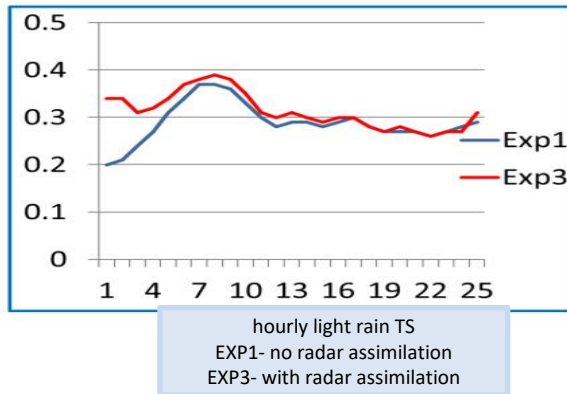


# Technical development – 1D+3D radar assimilation

- ◆ Linear combination of large-scale condensation and convection parameterization schemes using wet physical processes to form a 1D variational observation operator and to obtain reasonable humidity profiles.
- ◆ Introducing the obtained humidity profile as an observation into the analysis using 3D variational assimilation to obtain the initial field of the model.



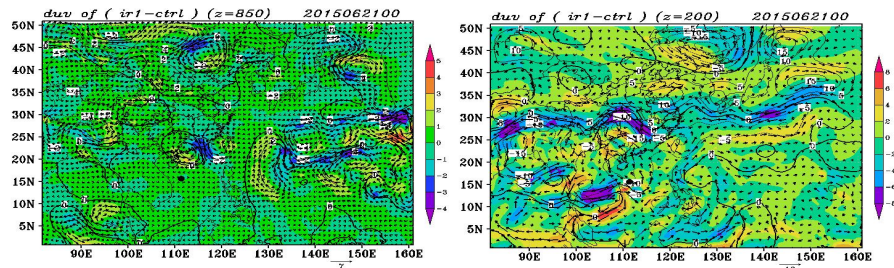
After assimilating radar water vapor, the precipitation score in the first 24 hours was improved





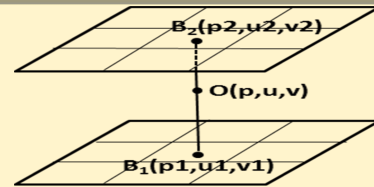
# Technical development – FY2E Satellite assimilation

- The FY2G TBB data was used in the cloud analysis system.
- The FY2E Cloud Guided Wind Data was used to correct the cloud height, which the cloud guidance wind could strengthen the southeast airflow on the east side of typhoon centers, which is conducive to guiding the typhoon center to move westward and obtaining the realistic typhoon path prediction.



201508 typhoon “Kujira” experiment

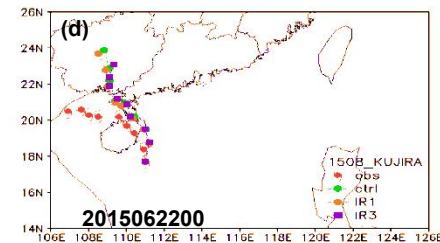
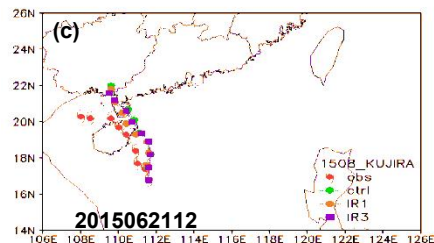
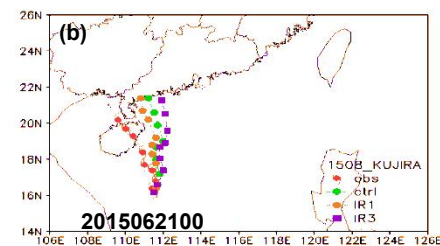
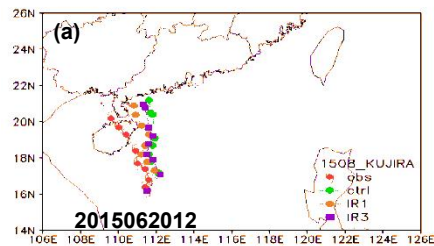
## FY2E Cloud Guided Wind Data



$$p' = \frac{W_2}{W_1 + W_2} p_1 + \frac{W_1}{W_1 + W_2} p_2$$

$$W_1 = \frac{(p-p_1)^2}{p} + \frac{(u-u_1)^2}{u} + \frac{(v-v_1)^2}{v}$$

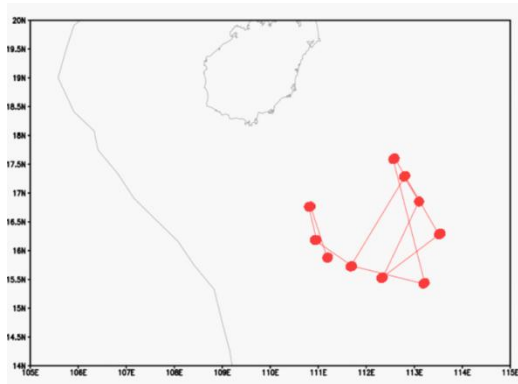
$$W_2 = \frac{(p-p_2)^2}{p} + \frac{(u-u_2)^2}{u} + \frac{(v-v_2)^2}{v}$$



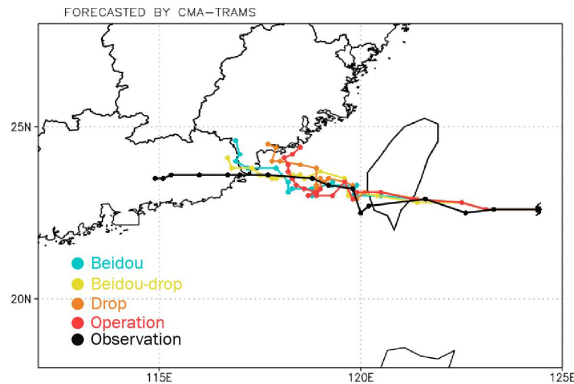


# Technical development – UAV and Beidou sounding experiment

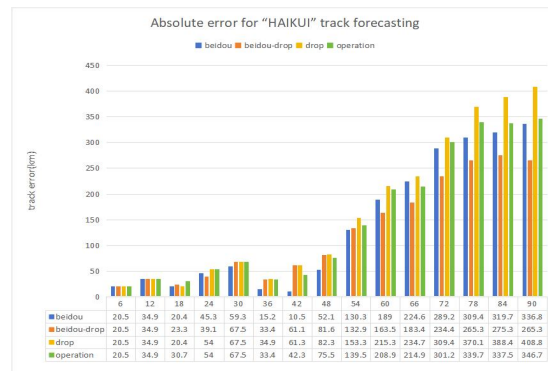
- The Unmanned Aerial Vehicle (UAV) drop sounding and Beidou sounding data was assimilated to examine the impacts on typhoon forecasting;
- The typhoon path forecast of HAIKUI turned westward after assimilating the UAV and Beidou sounding. The TS score was improved.



The UAV drop sounding Experiment (10 soundings)



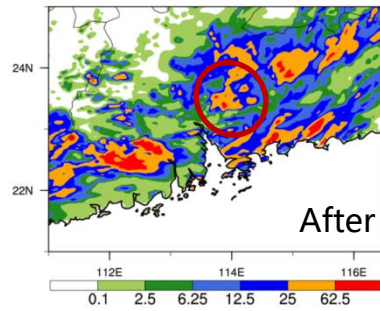
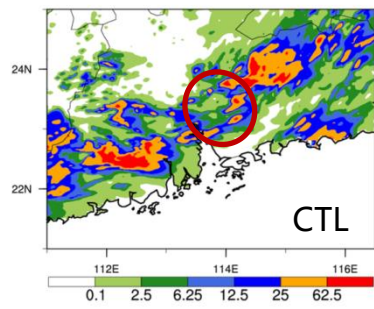
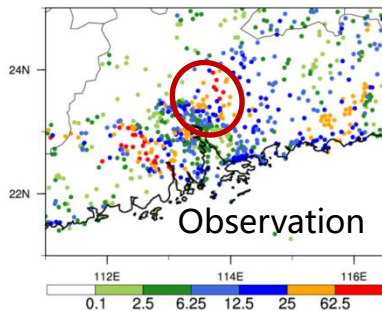
Comparison of typhoon forecast



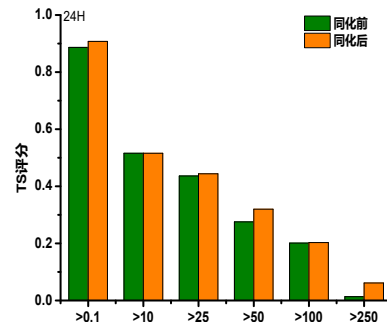
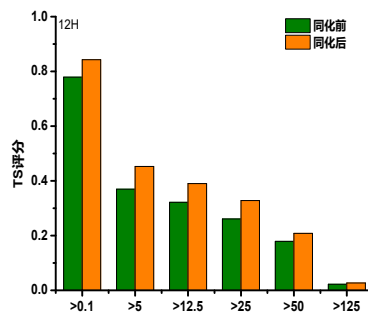
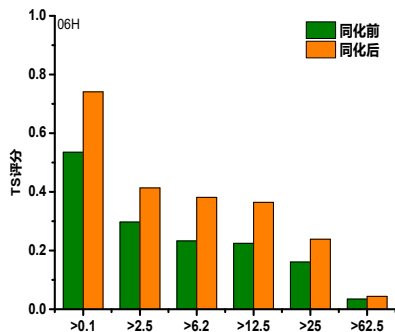
Typhoon track error

# Technical development – X-band phased array radar experiment

- Before assimilation, there was a large amount of false precipitation in northern Guangdong;
- After assimilation, the coastal precipitation on both sides of the the Pearl River Estuary can be better reflected.
- The TS score for the 6hour cumulative precipitation can be improved by the highest of 63.9;
- The TS score for the 12 hour cumulative precipitation can be improved by the highest of 25.7%.

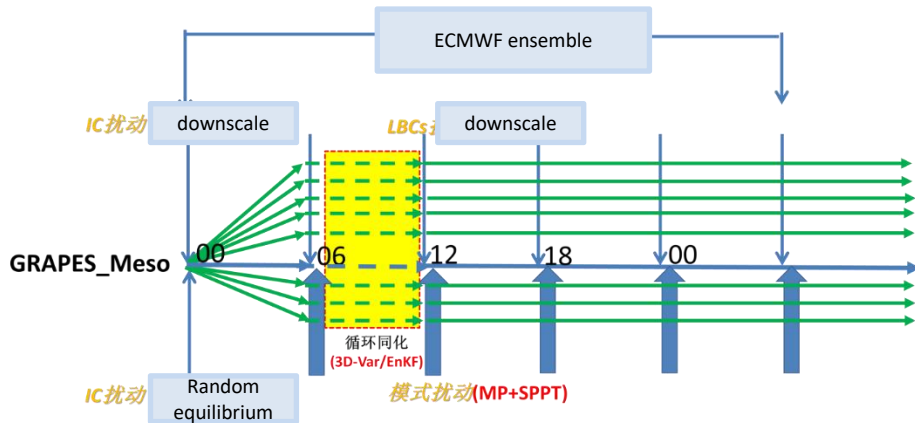
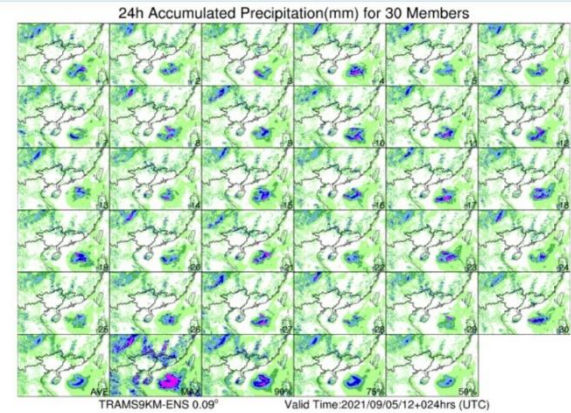


6h Accumulated precipitation

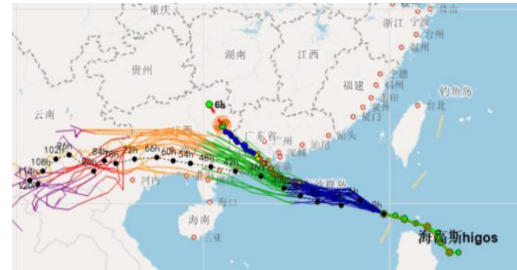


Average TS score of accumulated precipitation for 6h, 12h, and 24h

- ◆ Develop **different perturbation techniques** by considering scale characteristics and nonlinear interactions.
- ◆ Develop the "**combination of multi-source and multi type disturbances**" technology.
- ◆ A regional ensemble forecasting system based on TRAMS(CMA-TRAMS EPS) was running in operation with 30 members.

Regional ensemble forecasting system based on TRAMS(**CMA-TRAMS EPS**)

### CMA-TRAMS (EPS) 30 members of Precipitation Stamp Map



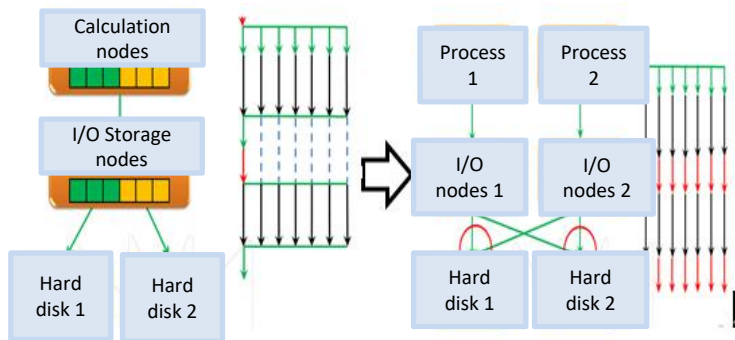
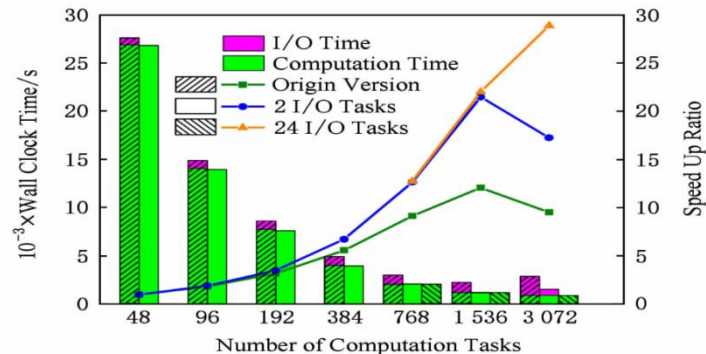
### CMA-TRAMS (EPS) typhoon track

# Technical development –High Performance computer

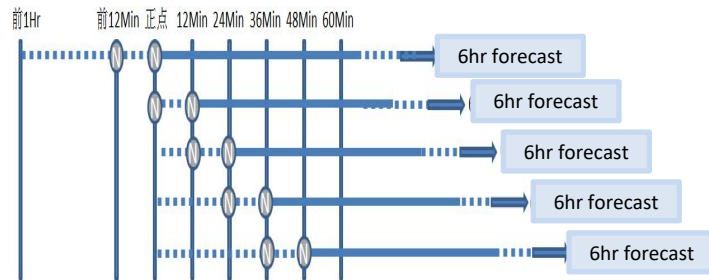


- ◆ Optimize **multi-process parallel I/O technology** and achieve higher computational efficiency to meet the requirements by 12 minute rapid update cycling based on "Tianhe 2"

- ◆ Developing multi process parallel I/O:
- ◆ The original output of a file takes 14 seconds, and after optimization, it takes 0.2 seconds.
- ◆ At present, the 1km model uses 100 computing nodes of Tianhe 2, completing a 6-hour forecast cycle within 8 minutes, which can meet the requirement of rapid updates in 12 minutes.



multi process parallel I/O

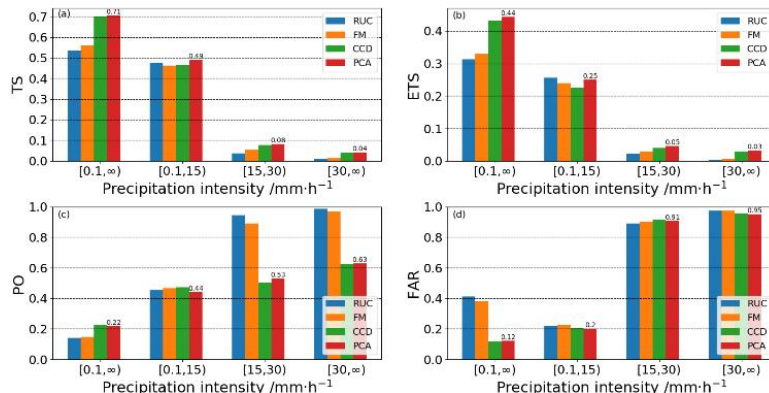
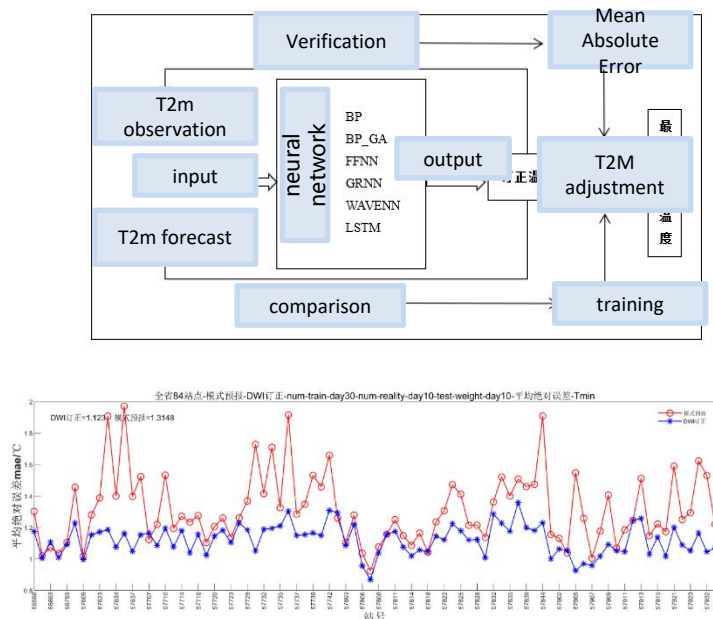


12 minutes updating and Nudging assimilation

# Technical development –Post-processing



- ◆ Systematic errors have been effectively alleviated by using a **random forest temperature correction** scheme and a **convolutional neural network** hourly precipitation prediction correction method, as well as an **AI dynamic weight integrated temperature** prediction scheme.

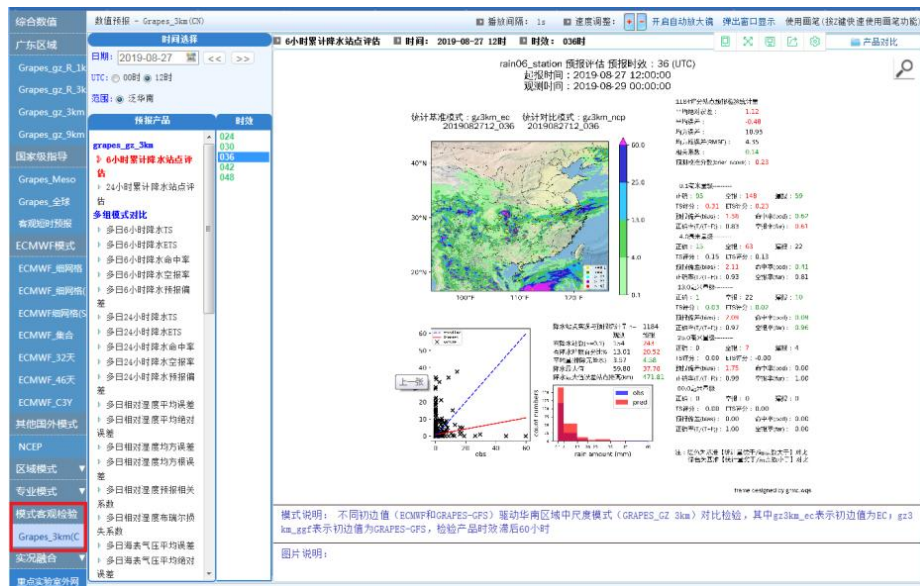


Precipitation correction method

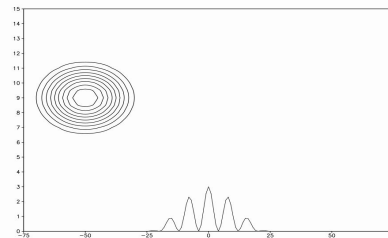
# Technical development –verification platform



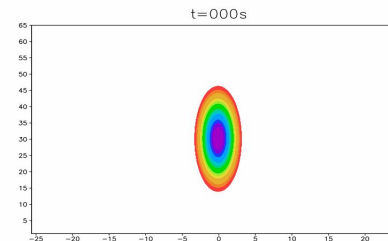
- ◆ Develop and establish a **verification, evaluation, and ideal experimental platform** to facilitate pattern development and version upgrade



Verification platform



Mass advection



Cold bubble

Ideal experiment-platform





**End of part 1**